Ecological determinants of occupancy and abundance of chinkara (*Gazella bennettii*) in Yadahalli Wildlife Sanctuary, Karnataka, India

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Chinkara (Gazella bennettii), the Indian gazelle, is a widespread antelope in the arid and semi-arid regions of the Indian subcontinent; however, the species has been relatively unexplored to the south of its distribution range. In 2016, with indefinite evidence of chinkara presence in Yadahalli Reserved Forest, Karnataka, India, the Forest Department notified the area as a Wildlife Sanctuary (WLS). We conducted a study to explore their possible existence and population status at Yadahalli WLS using a novel approach. We laid 2 sq. km grid cells in the Yadahalli WLS and divided it into four replicated sub-grids using GPS. We walked the grid cells and recorded the chinkara midden and deployed camera traps for direct detection and individual identity. We recorded site covariates, i.e. tree density, tree diversity, basal area, food tree density, cattle dung, goat and sheep droppings and distance from the boundary, and detection covariates, i.e. trail length. We performed occupancy modelling based on midden recordings using PRESENCE ver. 5.3. Through the effort of 62 grids with four spatial replicates, the detection probability of chinkara was found to be $0.68 \pm 0.03_{SE}$, and the estimated averaged occupancy was $0.51 \pm 0.37_{SE}$. The present study reveals a potential population of ~85 individuals in the Yadahalli WLS, which is the known southernmost population of the species in India. This study establishes the use of novel methods for monitoring of chinkara populations which will help in the development of a conservation action plan for the species and its habitat.

Keywords: Abundance, detection probability, *Gazella bennettii*, occupancy.

HABITAT composition and herbivore population dynamics have a mutual influence on each other, with ungulates being at the centre. On the one hand, habitat heterogeneity and resource distribution have been found to govern the ungulate populations¹⁻³, while on the other, herbivore assemblage has a long-term impact on the surrounding vegetation⁴. Halpin⁵ realized the importance of monitoring and documenting herbivore populations at both local and global scales. However, the methods for monitoring the individuals vary between species and the habitats they occupy. For example, ungulates residing in arid or semiarid landscapes in low density over vast open spaces are usually shy and highly vigilant, which makes it difficult to study them using conventional methods⁶. The Indian gazelle or chinkara (Gazella bennettii) is one such species which, despite being widely distributed in arid and semiarid regions, has been less studied in southern India because of its elusive behaviour and sporadic records.

Among the 19 species of gazelles found in Asia and Africa, chinkara is the only one found in the Indian subcontinent⁷. It is well adapted to, and is widespread in, the arid and semi-arid environs of the region⁸. The extent of its distribution in the subcontinent starts from northcentral Iran on the western side through Pakistan and Afghanistan, till the eastern states of India⁹. Its population is declining considerably in countries like Iran, Pakistan and Afghanistan¹⁰. In early 1960-70s, chinkara was found abundant in many districts of Balochistan, but during the last decade, its status has been affected severely by anthropogenic disturbances (viz. extensive poaching, livestock grazing) and land-use changes¹¹. In India, populations of chinkara have been found to be distributed in 11 states 12-15. Though the distribution is relatively widespread, the population is declining throughout its distribution range 16. This prompted to accord the highest

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protection (schedule 1) to the species under the Indian Wildlife Protection Act 1972 (ref. 17). The distribution of chinkara has been mostly studied in northern parts of India because of sporadic records from South India. In southern India, chinkara has been found to occur in certain parts of Karnataka^{12,18} and further south in the Coimbatore Forest Division, Tamil Nadu¹⁸. Subsequent studies did not record any population to the south of Pennar River, Andhra Pradesh, and a possible local extinction was supposed in large parts of Karnataka and Tamil Nadu^{12,19}. Thus knowledge about chinkara has been scanty. Although the distribution map of chinkara by Rahmani¹³ depicts a possible historical range in Karnataka, the range map in the IUCN website does not include Karnataka. However recently, Desai²⁰ reported the occurrence of chinkara from the Yadahalli Reserved Forest in Bagalkot district, which lies in the semi-arid region of Karnataka; this led to the reserved forest being notified as a Wildlife Sanctuary (WLS) in 2016. This was the first report in the last four to five decades about a possible occurrence of chinkara.

We conducted the present study to confirm the occurrence of chinkara based on the habitat covariates to further our understanding of the species at Yadahalli WLS. We employed methods suitable for this shy and elusive species in its natural habitat. Here, we report findings of the study conducted to assess the conservation status of chinkara in Yadahalli WLS using a methodology which could be standardized for further studies on the species throughout its distribution range.

Materials and methods

Study area

The Yadahalli WLS is located in northern Karnataka between 16°18′00″–16°23′47″N lat. and 75°24′00″–75°37′43″E long. (Figure 1). The sanctuary is spread over 96 sq. km. The temperature ranges between 14°C in December–January and 38°C in April–May and average annual rainfall is 580 mm (ref. 21). The vegetation of the study area includes southern dry mixed deciduous forest, southern thorn forest, southern thorn scrub, southern euphorbia scrub, babul forest and inundation babul forests²². The flora mainly consists of *Chloroxylon swietenia*, *Albizia amara*, *Wrightia tinctoria*, *Anogeissus latifolia*, *Acacia nilotica*, *Mundulea suberosa* and *Diospyros melanoxylon* as the dominant tree species²¹.

Field methods

The number of middens and the quantity of faecal deposits in an area indicate the occurrence and intensity of use by a species in that area. During our reconnaissance survey, we did not observe chinkara which is in agree-

ment to earlier reports from the study site²⁰. Hence, we opted for the occupancy framework by sampling middens and photographic captures of chinkara using camera trap technique, which is a reliable source for assessment of population status of shy and elusive animals⁶. A 'midden' is a site where chinkara defecate frequently 13. Detecting middens further avoided the confusion of detection with livestock, as neither goats nor sheep defecate at a common site. The Yadahalli WLS boundary was overlaid with 2 sq. km grid study on the 'geographical information system' platform using QGIS for camera trapping. The 2 sq. km grid size was chosen based on known home range of the species with similar forest structure, which was estimated to be ~2 km² (ref. 16). Each 2 sq. km grid was further divided into four sub-grids, which were used to sample middens. The Yadahalli WLS spanned over 65 grid cells, of which 36 were used for camera-trapping. Due to loss of camera traps during the initial phase, few peripheral grids close to human settlements were not sampled. Midden survey was conducted in 62 grids (Figure 1). The fieldwork was carried out during the dry season from February to May 2016.

Midden survey: We uploaded the shapefile of the grid cells to a handheld GPS (GARMINeTrex) using DNR Garmin application. Using this, the grid cells were located on the field. Once a grid cell was located, we selected the existing trail in the grid or randomly decided the walking path in order to cover the entire grid cell. We turned the track mode on to record the path in GPS and walked slowly by searching for middens. We sampled 62 grids and during the walk, we recorded the geocoordinates for all detections of middens using a handheld GPS receiver (Figure 1). We also determined the average visibility as it is considered to be one of the influencing factors for midden site selection for chinkara²³.

Camera-trapping: We used 30 'trail cameras' (HCO Scout Guard) and deployed five camera traps in each grid cell for five days. We placed one camera trap at the centre of each sub-grid and one at the centre of the main grid. The geo-coordinates for each camera trap location were recorded using a handheld GPS receiver. Apart from GPS readings of camera traps, data on time and date of camera deployment and removal, elevation of the area and terrain type were recorded. Camera traps were checked each morning to confirm the presence and assure proper functioning of the cameras. Camera traps were removed on the sixth day, and images were downloaded and organized according to grids and sub-grids.

Vegetation structure and anthropogenic variables: To assess the environmental and anthropogenic variables, we laid 10×10 m quadrats on a diagonal line within a grid cell. The quadrats were laid for 5 m either side of the diagonal line. The minimum distance between the two

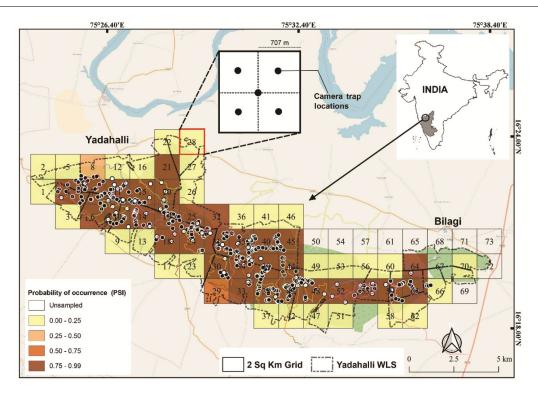


Figure 1. Map depicting location of capture, midden and probability of occurrence in each 2 sq. km grid at Yadahalli Wildlife Sanctuary, Karnataka, India.

Table 1. Predicted species response to each covariate based on our *a priori* hypothesis for chinkara

	Midden			
Covariates	Ψ	P		
TR	+	_		
FDTR	+	0		
BA	+	0		
DIVE	+	0		
CATT	_	0		
GOAT	_	0		
DIST	+	0		
KM	+	+		

TR, Tree density; FDTR, Food tree density; BA, Basal area; DIVE, Plant species diversity; CATT, Cattle dung density; GOAT, Goat drooping density; DIST, Distance from the boundary; KM, Trail length. '+' signifies a positive effect on the response variable, '-' signifies a negative effect and '0' signifies that the covariate does not affect the response variable. '—' Not applicable. ψ is the probability of occurrence and P is the species detection probability.

quadrats was 400 m across the diagonal line. Plant species having minimum 0.10 m girth were considered as trees, and height of the trees was measured using a hypsometer. The girth at breast height (GBH) for each stem more than 0.10 m was measured. Number and area covered by bushes in each quadrat were recorded. Taxonomic identification of the species was done follow-

ing *Flora of Karnataka* by Saldanha²⁴. We also recorded the count of dung piles of livestock in quadrats. On the GIS platform, we measured the distance of the grid corner to the forest boundary and the nearest village.

Statistical analysis

A priori hypothesis: Considering the biology of chinkara and habitat conditions, an a priori hypothesis was established to determine the parameters that might influence their detection and occupancy in the grid cells (Table 1). We categorized site-level covariates as ecological variables: tree density (TR), tree diversity (DIVE), basal area (BA) and food tree density (FDTR); anthropological variables: cattle dung (CATT), goat and sheep droppings (GOAT) and distance from the boundary (DIST). We used trail length (KM) as a covariate for detection probability.

Independent variables: Using plant data from each quadrat we calculated TR and FDTR by dividing the total number of individuals/area sampled \times 10,000 and BA using the formula $(GBH)^2/4\pi$. The plant species diversity (DIVE) was represented by Shannon-Wiener's index using the formula

$$H' = -\sum (n_i/N) \ln(n_i/N),$$

for each grid cell. We listed five species as the most important food species for this study area based on the

Table 2. Detection probabilities for chinkara midden

Model	$\hat{p} \pm SE$	AIC_c	AIC_c	w_i	K	Naïve occupancy
$\psi(.), p(KM)$ $\psi(.), p(.)$	0.68 ± 0.03 0.70 ± 0.04	225.20 229.58	0.00 4.38	0.90 0.10	3 2	0.44

 \hat{p} , Estimated species detection probability; AIC_c, Akaike information criterion corrected for small-sample bias; Δ AIC_c, Difference in AIC_c values between each model and the model with the lowest AIC_c, w_i , AIC_c model weight; K, Number of parameters estimated by the model and KM, Trail length.

Table 3. Model for occupancy of chinkara using midden

Model	ŵ	SÊ	AIC_c	ΔAIC_c	w_i	K
ψ (BA + CATT + DIST), p (KM)	0.5161	0.3710	170.95	0	0.6519	4
ψ (BA + CATT), p (KM)	0.5125	0.0522	173.28	2.33	0.2033	4
$\psi(BA), p(KM)$	0.5280	0.0347	173.96	3.01	0.1447	2
ψ (DIST), p (KM)	0.4821	0.0486	210.33	39.38	0	2
ψ (DIVE), p (KM)	0.5082	0.0471	212.76	41.81	0	2
ψ (CATT), p (KM)	0.5087	0.0483	213.02	42.07	0	2
ψ (GOAT), p (KM)	0.5175	0.0502	217.12	46.17	0	2
ψ (FDTR), p (KM)	0.4995	0.0479	224.32	53.37	0	2
$\psi(TR), p(KM)$	0.4993	0.0479	224.32	53.37	0	2
$\psi(.), p$ (KM)	0.4744	0.0643	225.20	54.25	0	2

 $\hat{\psi}$, Estimated occupancy parameter; $S\hat{E}$, Associated standard error.

literature and using our field observations to calculate FDTR. DIST, CATT and GOAT were considered as independent variables which may affect habitat selection of chinkara. We considered the variation in trail length to be the influencing factor for detection rate of middens.

Occupancy and abundance modelling: The detection of middens in each sub-grid was considered as a spatial replicate, and the capture of chinkara in each 24 h cycle for five days was considered as a temporal replicate. A binary presence/absence matrix of detection history was constructed for middens and captures by camera traps. The detection probability, occupancy and abundance were computed using PRESENCE software v.5.3 (USGS, USA). Assuming the population was closed during sampling, single-season occupancy modelling was used for the estimation of detection probability (P) and proportion of sites occupied (ψ).

Models were first developed to check whether the site covariates affect the detection probability. A null model was developed keeping the detection probability constant $p(\cdot)$ for each site covariate. Then the model was compared with other models (site-covariates) to estimate the detection probability. The models were ranked according to the Δ AIC (Akaike information criterion) value. The lowest Δ AIC value was ranked highest²⁵, and the average of all the models was calculated to estimate the final occupancy. Generalized linear modelling (GLM) was carried out for the estimation of determinants for the relative abundance of chinkara middens. The modelling was performed using R v 3.5.1 software²⁶.

We estimated the abundance of chinkara for the sampled area using Royle and Nichols model²⁷ in

PRESENCE v5.3 (USGS, USA) using capture data from camera traps. Further, using the estimated abundance in the sampled area, we extrapolated to other areas occupied by the chinkara using occupancy models deduced from middens. Captured photographs were examined for identification of individuals, and differentiating between males and females based on the differences in horn size and annuli pattern. The shape and annuli number of horns, and some morphological characters like marks on the body and wound scars, were used to identify the individuals. The sex ratio was computed using data on age—sex of the individuals and their identity.

Results

A total of 217.73 km was covered by walking in the 62 grids, during which we recorded the middens of chinkara in 30 grids. We recorded a total of 357 middens of chinkara in 60 sq. km (30 grid cells). The average visibility range around a midden was 3359 sq. m, which ranged between 198 and 20,700 sq. m². Largely, the middens were placed at 'relatively open area' within thick vegetation

The analysis from 62 sites with four sampling occasions provided an estimated detection probability (p) of 0.68 ± 0.03 for the middens (Table 2). The distance walked (KM) in each sub-grid influenced the detection probability of middens, i.e. $w_i = 0.90$. Subsequent models were run with KM as a function of p. The estimated naïve occupancy was 0.40. The estimated occupancy for middens was $\psi(.)$, $p(.) = 0.51 \pm 0.37$. Since w_i of the top model was more than 0.5, we did not sum the AIC_c

wt. and considered the top-ranking model as a predictor (Table 3). The occupancy of chinkara was positively correlated with BA: β = 8.93 ± 5.15 and DIST: β = 2.22 ± 1.59, while CATT had a negative influence ' β = -2.57 ± 2.15' (Table 4). The site occupancy estimates were classified as low ($\hat{\psi}$ = 0.00–0.25), medium ($\hat{\psi}$ = 0.25–0.50), high ($\hat{\psi}$ = 0.50–0.74), very high ($\hat{\psi}$ = 0.74–0.99), and mapped, which shows that 33 out of 62 grids have a high probability, while 29 grids show relatively less probability of occupancy of chinkara in the study site (Figure 1).

GLM revealed BA as a significant determinant for relative abundance of chinkara. A model involving only BA was found to be the most suitable when compared with combinations of other covariates (AIC_c = 163.14; Table 5). Areas with high abundance of chinkara correspond to high BA (β = 0.79 ± 0.29).

A total of 83 animals were identified in 72 sq. km of the area with a mean herd size of $1.20 \pm 0.51_{\rm SD}$ individuals, which varied between 1 and 4. According to the Royle and Nichols model²⁷ ($r = 0.29 \pm 0.06_{\rm SD}$ and $\lambda = 1.50 \pm 0.39_{\rm SD}$), abundance in the sampled area was estimated to be 54.00. The individuals in each sampled grid were not detected in the neighbouring grids, except two adult males which were detected at the border of the adjoining grids. We multiplied site abundance with the mean herd size, which provided an estimate of 64 animals in 72 sq. km area. We extrapolated this estimate to other unsampled grids to approximate the possible population size in Yadahalli WLS, which was 85 animals in 96 sq. km of the sanctuary.

Discussion

Many of the antelopes have evolved and adapted for the plains, but also live in open scrub forests and productive landscapes. Chinkara is one among them known to extend from the Thar Desert to open scrub forests. Various studies have been conducted in different habitat types to estimate their density, like road surveys in desert areas and productive fields in Rajasthan^{13,14,28,29}; line transects in the forested areas or protected areas with forest cover in Kutch and Gir in Gujarat, and Ranthambore Tiger Reserve in Rajasthan^{30–32}, but there has been a lack of consistency in the results. Estimates using road surveys for different studies in Rajasthan varied highly (Table 6). Except in the Gogelao Enclosure in Nagaur³³ and Ranthambore Tiger Reserve³⁰, the estimated density of

Table 4. Covariates influencing chinkara occupancy on basis of β -coefficients and standard error

Covariate	β -coefficient	SÊ
Basal area (BA)	8.93	5.15
Distance (DIST)	2.22	1.59
Cattle (CATT)	-2.57	2.15

chinkara for all the sites was less than 3 individuals/sq. km, including the Yadahalli WLS. The present population density estimate indicates the existence of a sizable population in the Yadahalli WLS.

Results confirm the home range size of a herd or an individual chinkara in Yadahalli WLS to less than or equal to 2 sq. km, as the individuals were not found outside the border of the grids or neighboring grids. This is in agreement with Dookia¹⁶, who reported 2 sq. km of home range size in scrub forests of Rajasthan. Further, the Royle and Nichols model²⁷ deduced a density of 0.88/sq. km, which corresponds to minimum population size derived from total count made using the photocapture technique (0.86–0.99/sq. km).

Chinkara live in small herds of about 2–3 individuals, with mean herd size varying between 1.2 in Yadahalli, Karnataka and 2.60 in Ranthambore, Rajasthan³⁴ and Kachchh, Gujarat³². However, a mean herd size of 5.01 was reported in Mayureshwara WLS, which is a small protected area notified to protect chinkara³⁵. Probably, the high protection and limitations of the area have positively influenced the herd size in Mayureshwara WLS. Although the herd size in the present study is comparatively smaller, our estimates are highly reliable due to the use of infrared cameras used for camera-trapping technique.

The sex ratio was biased towards females in most of the range (Table 6); however, it was negative in Ranthambore (1:0.83) and Yadahalli (1:0.83), while adult female to fawn ratio did not differ between the sites (0.15–0.35). This requires further exploration to understand the population dynamics and survival rate of chinkara under different ecological conditions.

In Yadahalli WLS, the occupancy and abundance of chinkara were determined by the BA. However, the record of midden sites shows that they choose small, open areas which are the centre of their activities. As they feed on leaves from many shrubs and small trees, they were found more in the higher basal area, and further, they choose small, open areas within good forest cover. Thus, basal area is an important covariate which positively influences the occupancy and abundance of chinkara in Yadahalli WLS.

Conclusion

This study establishes the presence of chinkara in the southern extremity of its distribution. Being an arid environment species with ~2 sq. km home range, the chinkara can have a healthy population even at low densities, making its monitoring difficult. This study demonstrates methodologies which can be employed to survey low-density populations of an elusive species through the use of camera traps and survey of middens. Further, these methods can also be employed for periodical monitoring

Table 5.	Summary of the model selection procedure for covariates influencing relative abundance of chinkara with
	R^2 and corresponding P values, β -coefficients and associated standard errors

Covariates	R^2	P	AIC _c	ΔAIC_c	K	β -coefficient	SÊ
BA	0.1780	0.000	163.14	0	1	0.7914	0.2917
BA + DIST	0.1781	1.600	165.13	1.99	2	0.4085	0.3574
BA + DIST + CATT	0.1840	4.391	166.87	3.73	3	0.2462	0.2483
TR	0.0797	0.000	167.20	4.06	1	0.0028	0.0017
DIVE	0.0482	0.002	168.41	5.27	1	2.4550	1.8720
CATT	0.0383	0.005	168.79	5.65	1	-0.0046	0.0040
FDTR	0.0098	0.160	169.84	6.70	1	0.0016	0.0029
DIST	0.0072	0.229	169.93	6.79	1	0.2188	0.4414
GOAT	0.0006	0.745	170.17	7.03	1	0.0006	0.0045
BA + DIST + CATT+ GOAT + TR + FDTR + DIVE	0.2453	1.856	172.06	8.92	7	0.1769	0.5569

Table 6. Density and other variables of chinkara in other study sites

Location	Method	Density (km ⁻²)	Herd size	Ratio (M:F)	Ratio (F : fawn)	Reference
Thar Desert, Rajasthan	Road survey	0.74	1–3	1:1.3	_	12
Thar Desert, Rajasthan	Road survey	0.74	_	-	_	28
Thar Desert, Rajasthan	Road survey	0.89	_	_	_	29
Thar Desert, Rajasthan	Road survey	1.09	_	-	_	14
Thar Desert, Rajasthan	Road survey	0.76	_	1:2.20	_	14
Mayureshwara Wildlife Sanctuary, Pune	Road survey	-	5.01	-	-	35
Gogelao Enclosure, Nagaur, Rajasthan	Line transect	48.4 49.6	-	1:1.45	-	33
Kachchh, Gujarat	Line transect	0.005	2.55	1:1.46	_	32
Gir, Gujarat	Road strip count/line transect	1.20	2.22		_	31
Narayan Sarovar Chinkara Sanctuary, Gujarat	-	1.25	-	1:1.35	-	36
Narayan Sarovar Chinkara Sanctuary Gujarat	_	2.89	-		1:0.15	37
Ranthambore, Rajasthan	Line transect	5.60	2.5 - 2.6	1:0.83	1:0.35	30
Cholistan Game Reserve, Pakistan	_	0.16	_	1:1.75	_	38
Yadahalli WLS, Karnataka	Photo-capture	0.88	1.20	1:0.83	1:0.24	Present study

of chinkara and other antelopes. As ungulate densities and vegetation are interdependent, their period monitoring will help understand the health of the ecosystem and establish management practices.

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