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Tutorial: Cavity Quantum Optomechanics

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Exploring quantum physics in mancroscopic systems and manupulating these systems for various technological applications has been a topic of intense research in the last one decade or so. In this regard, the field of cavity quantum optomechanics turns out to be one of the most rapidly emerging area of research. It has opened many doors to study various open ended fundamental questions in quantum physics, apart from numerous possible applications. A typical cavity optomechanical system consists of two mirrors, one fixed while the other one is movable. These systems may be of micrometer or nano-meter in dimensions. The electromagnetic radiation incident on the system may get coupled to the mechanical motion of the movable mirror. This opto-mechanical coupling is the root of all phenomena such as quantum entanglement, state-transfer, squeezing and so on. In this short tutorial, basic concepts of cavity quantum optomechanics are discussed. We hope that this tutorial would motivate readers, both theorists and experimentalists, to take up advanced studies in this immensely fruitful area of research.

Keywords: Optomechanics; Cavity system; Quantum rntanglement; Squeezing

1 Introduction

Cavity quantum optomechanics is a rapidly evolving research area of physics, and science in general $1,2$. This field of research requires utilization of the tools of quantum optics in a variety of condensed matter systems. In the rest of the article, we use the term 'optomechanics' frequently, to mean cavity optomechanics or cavity quantum optomechanics. Optomechanics deals how light couples with mechanical motion. There are mechanical systems, such as beams, cantilever etc, on micro and nano scale, that can vibrate in the frequency range of kHz to GHz. Over the past two decades or so, researchers have learnt how to control these systems, i.e. to couple them and read out their motion, by a variety of methods. One of the first such approach was to couple these motions to electrical circuits, resulting in the so-called nano electrical mechanical systems $(NEMS)^3$. Later, similar endeavours led to couple these systems to electromagnetic field in the optical domain, giving birth to the area of optomechanics. At the root of optomechanical interaction is the so-called radiation pressure induced interaction between photons and mechanical motion in a cavity^{4,5}. The radiation pressure force, arising due to the momentum carried

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by light, can displace a movable end mirror of the cavity. This in turn changes the length of the cavity, resulting in modification of the cavity frequency. With the rapid advances in micro and nanofabrication techniques, this nonlinear interaction has led to the exploration of a wide variety of interesting phenomena both theoretically and experimentally, such as squeezing of the light field and mechanical motion, entanglement between optical and mechanical modes, bistability, optomechanical normal mode splitting, optomechanically induced transparency, and so on.

Optomechanics turns out to be potential tool to probe fundamental physics and to exploiting its various concepts for various applications, primarily in the so-called quantum technologies⁶. Optomechanics can be used to test quantum mechanics in an entirely new domain. It is possible to produce non-classical states of heavy mechanical objects and test Quantum Mechanics. One of the fascinating topics of research where optomechanics could be useful is to get an idea about so-called transition boundary between the classical world to quantum world or vice versa. To put in a simple language, to know, when to stop using Newton's laws and use Schrodinger's formalism etc. For heavy objects we generally do not talk about quantum mechanics. As we go to larger and larger objects they couple to the unavoidable fluctuations of noisy environment more strongly resulting in the

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destruction of superposition and leading to decoherence. If the objects are large enough decoherence may not even allow us to produce superposition of states in the first place. One primary goal is to test how decoherence evolves for heavy objects. There is a speculation, primarily due to British mathematician and physicist Roger Penrose, that if we go to heavier objects additional mechanism for decoherence might kick in owing to gravitation! This may enable us to look into various aspects of quantum gravity⁷.

The reason for enormous popularity of optomechanical systems (OMS) and its variants is numerous possible applications, primarily in quantum technologies 6.8 . OMS may be used for quantum information processing, *i.e*. to store quantum information and transfer it. One can couple a superconducting qubit to a mechanical system and then couple it to an optical system to process the information. It is important to note that to study the quantum states of such systems, we need to cool these mechanical systems. Because their vibration frequency ω_m lies in the range of kHz-GHz, which corresponds to temperature $T \approx h \omega_m / k_B$ that lies far below 20 mK or so, we need to look for some clever methods to cool mechanical systems. It is good to reduce thermal fluctuation but not always necessary to go to quantum ground state as regards applications are concerned. As an example, for the last 20 years or so, cantilevers are used in atomic force microscopy. The idea is to use these cantilevers to scan across the surface of some material and look at the surface of the material with atomic resolution. Ultra sensitive detection of tiny forces (force gradients to be precise. Because if we apply a force gradient to an oscillator it adds some effect to the spring constant of the oscillator and shifts the frequency which is easy to detect), masses, displacement etc. is also demonstrated using OMS. It is well known that interaction of light field and the mechanical system automatically provide some nonlinearity. So, whenever we have a dynamical system with nonlinearity, by proper driving we can turn it into an amplifier. Thus, we can amplify very small signal, and indeed OMS are used in signal amplification and processing. The best thing about optomechanical systems is that everything could be integrated on a chip and nano-fabrication of these devices is possible⁹. The primary advantages of optomechanical platforms over that of other ones are due to its small size, high quality factor (as a result, information

can be stored for a very long time) and its integrability with various other systems¹⁰. Moreover, mechanical system can be coupled to virtually α anything — qubits, superconducting circuits, spins, cold atoms *etc*.

It is obvious that, owing to the enormous significance of the field of cavity optomechanics, and the fact that the field is developing pretty fast since the last decade, there are numerous review articles, short notes, book chapters and so on. Even, there are quite a few online materials by experts. The objective of this tutorial is to give the readers a comprehensive introduction to the key concepts of cavity quantum optomechanics, which would surely motivate them to take up further studies.

2 Mechanical Effects of Light

The radiation pressure force is at the root of all optomechanical phenomena. In fact, radiation pressure force is behind the most well known optical tools called optical tweezers, frequently used by biologists. Arthur Ashkin of Bell Labs contributed significantly towards understanding of radiation pressure force¹¹.

2.1 Radiation Pressure Force

A typical set-up to explain the radiation pressure force is depicted in Fig. 1 (a). A photon incident on a perfectly reflecting mirror gives a momentum kick of ¯*hk* to the mirror and while it gets reflected experiences a momentum kick, ¯*hk* from the mirror. Thus it experiences an overall momentum change given by the equation.

$$
\Delta p = 2\hbar k = 2\frac{\varepsilon}{c} \qquad \qquad \dots (1)
$$

Here E is the energy of the single photon. If we have a steady stream of photons then the force will be:

Fig. $1 - Two examples of mechanical effects of light:$ (a) radiation pressure force and (b) dipole force.

Here N_p is the number of photons impinging on the mirror and *P* refers to power. For example, the radiation pressure force due to sunlight is nearly on the order of 10^{-5} Newtons on one square meter, a very tiny force!

2.2 Dipole Force

Dipole force is another example of a radiation pressure force. Take two counter propagating light waves. They will form a standing wave, where the intensity of the resultant wave will vary sinusoidally. If an atom or any polarizable object is placed in the light wave, then the electric field will induce some dipole moment in the atom. The atom, in turn then will interact with the electric field, $\overline{E}(t)$. The energy, E, of the dipole placed in the electric field is given by:

$$
\varepsilon = -\vec{\mu}(t) \cdot \vec{E}(t) \propto \pm |E|^2 \qquad \qquad \dots (3)
$$

the dipole moment being proportional to the electric field intensity. The sign depends on the direction of the laser electric field and the dipole moment. That again depends on how laser frequency lies with respect to the atomic transition frequency. When the sign is negative (laser light is red-detuned) the atom will be dragged towards higher intensity. On the other hand, if the laser light is blue-detuned; atom will be pushed towards lower intensity. This technique is used to trap atoms or molecules or polarizable particles: Atoms in standing light wave is called Optical lattice.

3 Generic Model of an Optomechanical System

Although there are numerous platforms where optomechanical effects could be realized, a

surprisingly simple model can be used to describe all the phenomena displayed by those seemingly different platforms. Such a model, as depicted in Fig. 2, is a cavity with two mirrors — one fixed and the other moveable, separated by some distance $(say L)$ — and driven by a laser source (say, with amplitude A_l and frequency ω_l ¹. The cavity boosts the light field injected inside it by the laser and the radiation pressure force of the intracavity photons results in a continuous transfer of momentum to the mechanically-compliant end mirror. This gives rise to mechanical degrees of freedom, whose individual movements are given by the response of elastic strain in their harmonic modes⁷. But the macroscopic displacement of the mirror largely depends on the shorter-wavelength microscopic phononic modes, and the collective degrees of freedom can be described by a single mechanical mode. Hence, the mechanical mirror can be approximated to oscillate with an effective resonance frequency of ω_m and an effective mass of *m*. One can then focus on that single optical mode of the cavity (say with frequency $\omega_{o} = n\pi c/L$ with mode number *n*) which is close to the laser frequency. For a mechanical displacement of ˆ*x*, the new cavity resonance frequency can be expressed as

$$
\omega_c(\hat{x}) = \frac{n\pi c}{L+\hat{x}} = \frac{\omega_o}{1+\hat{x}/L} \approx \omega_o \left(1-\frac{\hat{x}}{L}\right) \quad \dots (4)
$$

This relationship gives us the frequency pull parameter¹ $G = \partial \omega_c(x) / \partial x^{\hat{}} = \omega_c / L$, which quantifies the linear dispersive shift of the resonance frequency of the optical field induced by the mechanics. It is important to note here that a driven cavity with two fixed mirrors only accomodates modes having

Fig. 2 — Illustration of a typical optomechanical cavity with relevant parameters⁸.

frequencies in integral multiples of $\pi c/L$ — a parameter called the free spectral range (FSR) of the $cavity²$. For most optomechanical systems, this value is much larger than the mechanical frequency.

3.1 Hamiltonian Formalism

The total Hamiltonian, *H*, of a typical optomechanical system consists of the contributions from the optical components, the mechanical components, the interaction between the optics and the mechanics, the laser drive and the transfer of photons and phonons to and from the environment. Let us derive each of these terms one by one.

The optical and mechanical modes can be represented as harmonic oscillators with annihilation operators ˆ*a* and ^ˆ *b* respectively. Each of these operators obey the Bosonic commutation relations $[O^{\hat{}}O^{\hat{}}] = 1$ with their number operators given by $\hat{c}_{n_0} = O^{\hat{c} \dagger} O$. Thus, one can write the energy of the optical (mechanical) mode in terms of the number of photons (phonons) times the energy of each quanta, and obtain the combined Hamiltonian of the optical and mechanical modes as

$$
\begin{aligned} \hat{H}_{om} &= \hbar \omega_c(x) \hat{a}^\dagger \hat{a} + \hbar \omega_m \hat{b}^\dagger \hat{b}, \\ &= \hbar \omega_o \hat{a}^\dagger \hat{a} + \hbar \omega_m \hat{b}^\dagger \hat{b} + \hat{H}_{int} \end{aligned} \tag{5}
$$

where we have used Equation (4) to write the Hamiltonian describing the interaction between the optical and mechanical modes as

$$
\hat{H}_{int} = -\hbar G \hat{x} \hat{a}^{\dagger} \hat{a} = -\hbar_{g0(\hat{b}^{\dagger} + \hat{b})\hat{a}^{\dagger} \hat{a} \qquad \dots (6)
$$

Here, we have introduced the optomechanical coupling constant [1]

$$
g0 = Gxzp = G \sqrt{\frac{\hbar}{2m\omega_m}} \qquad \qquad \dots (7)
$$

where x_{ZP} is the zero-point position and is typically of the order of 10^{-15} m. This coefficient relates the radiation pressure force of a single photon on the position of a phonon and can range from a few Hz to a few MHz.

Exercise: Obtain the radiation pressure force and its relationship with the frequency pull parameter using the Hamiltonian in Equation (5).

We now add the laser drive term which describes a photon created inside the cavity at the laser frequency and its Hermitian conjugate. Thus, we obtain the effective Hamiltonian for the system as

$$
\hat{H}_{sys} = \hbar \omega_o \hat{a}^\dagger \hat{a} + \hbar \omega_m \hat{b}^\dagger \hat{b} - \hbar_{g0\hat{a}^\dagger \hat{a} (\hat{b}^\dagger + \hat{b})} \dots (8)
$$

= $i \hbar A_l (\hat{a}^\dagger e^{-i\omega_l t} - \hat{a} e^{i\omega_l t})$

The time-dependent terms in this Hamiltonian can be removed by switching to the rotating frame of the laser. This transformation also helps us to analyze the slower dynamics of the mechanical motion. We obtain the Hamiltonian in this frame as

$$
\hat{H}_{sys} = -\hbar\Delta_o \hat{a}^\dagger \hat{a} + \hbar\omega_m \hat{b}^\dagger \hat{b} - \hbar_{g0\hat{a}^\dagger \hat{a} (\hat{b}^\dagger + \hat{b})} \dots (9)
$$

$$
= -i\hbar A_l (\hat{a}^\dagger - \hat{a})
$$

where $\Delta_0 = \omega_l$ ⁻ ω_o is the *laser detuning* and the operator ˆ*a* is written in the rotating frame.

Exercise: Choose an appropriate unitary transformation and derive Equation (9).

Typically, the resonant frequency of the cavity (ω_o) is on the order of 10^{15} Hz, whereas the mechanical resonance frequency (ω_m) is usually in the range of MHz to GHz. The laser frequency is therefore adjusted in such a way that its detuning Δ_0 is comparable to ω_m . Also, since the optical frequencies are very high, the effect of the thermal photons entering the cavity can be safely neglected and the cavity can be considered to be coupled with a reservoir at zero temperature. However, the laser drive does introduce noise into the system. On the other hand, thermal phonons play a very important role on the quantum dynamics of the mechanical mode. We explore these environmental effects systematically in the next section. Also, note that we shall drop the operator symbol in the rest of the article to make the expressions simpler.

3.2 Quantum Langevin Equations

Optomechanical cavities are open quantum systems. Such systems interact with the environment and undergo fluctuations and dissipations^{7,12}, resulting in the decay of photons, mechanical damping as well as insertion of environmental noises.

3.2.1 Dissipation Processes

Since the photons are coupled to the external environment through the mirrors, they experience absorption and scattering losses. These losses collectively define the optical decay rate *κ*. The optical deacy rate also determines the quality factor of the cavity, which is given by $Q_0 = \omega_0 / \kappa$. This factor signifies the total number of times a single photon oscillates inside the cavity before moving out. Similarly, the mechanical motion is affected by environmental factors such as viscous drag, clamping losses, phonon-phonon interactions and losses due to its composition. The mechanical damping rate *γ* takes these effects into account. It also characterizes the

strength of coupling between the mechanical mode and the environment. The mechanical quality factor $Q_m = \omega_m / \gamma$ is equivalently related to the phonon lifetime.

3.2.2 Input Fluctuations

As mentioned earlier, the environment also introduces noises into the system and steers the system dynamics. However, such a thermal environment could be modelled by a bath of several non-interacting harmonic oscillators. Effectively, the noises entering the system can also be approximated as Markovian, zero-mean and *δ*-correlated. It is useful to note that a system is termed as Markovian if its present state does not depend on previous history. Moreover, zero-mean and *δ*-correlated noise are known as *white noise*. Therefore, the white noise entering the cavity through the laser drive (a_{in}) and the *Langevin noise* introduced into the mechanical oscillations (b_{in}) follow the standard correlation relations⁷:

$$
\langle a_{in}(t)a_{in}^{\dagger}(t^{\prime})\rangle = \delta(t - t^{\prime})
$$

\n
$$
\langle b_{in}^{\dagger}(t)b_{in}(t^{\prime})\rangle = n_{th}(t - t^{\prime})
$$

\n
$$
\langle b_{in}(t)b_{in}^{\dagger}(t^{\prime})\rangle = (n_{th} + 1)\delta(t - t^{\prime})
$$
 (10)

where $n_{th} = [\exp\{h\omega_m/(k_B T)\} - 1]^{-1}$ is the mean thermal occupancy at bath frequency ω_m and temperature *T*. k_B is the Boltzmann constant.

3.2.3 Input-Output Relations

Although the photon energy decay rate κ is a collective term, it is predominantly associated with the input-output losses than the intrinsic cavity losses. As such, the optical field amplitude effectively decays at the rate $\kappa/2$. Also, it is important to note here that input-output theory relates the laser power P_l entering the cavity to the amplitude inside it as $A_l = \frac{P_K P_l}{\hbar \omega_l}$. The input power associated with the white noise is given by $P_{in} = \hbar \omega_l \langle a^{\dagger}_{in} a_{in} \rangle$. With the mean-field approximation for this input noise, it follows that the optical mode is modulated by an ex-tra amount of κa_{in} . The input-output relation is then obtained as¹²:

$$
a_{out} = a_{in} - \sqrt{ka} \qquad \qquad \dots (11)
$$

where a_{out} is the measured field exiting the cavity through the mirror.

3.2.4 Equations of Motion

Using the Hamiltonian of the system derived in Equation (9) and the expressions for fluctuations and

dissipations, we obtain the quantum Langevin equations (QLEs) corresponding to the cavity field and the mechanical mode as^7 :

$$
\dot{a} = -i \left[a, H_{sys} \right] - \frac{k}{2} a + \sqrt{k a_{in}}
$$

\n
$$
= -\frac{k}{2} a + i \Delta_0 a + i g_0 (b^{\dagger} + b) a
$$

\n
$$
+ A_l + \sqrt{k a_{in}},
$$

\n
$$
b = -i \left[b, H_{sys} \right] - \frac{\gamma}{2} b + \sqrt{\gamma b_{in}}
$$

\n
$$
= -\frac{\gamma}{2} b + i \omega_m b + i g_0 a^{\dagger} a + (\sqrt{\gamma b_{in}} \qquad \dots (12)
$$

Exercise: Using the Bosonic commutation relations, derive Equations (12).

It can be seen here that the frequency shift introduced in the optical mode by the mechanical position changes its amplitude, which in turn changes the mechanical mode amplitude. Both of these phenomena depend directly on the optomechanical coupling constant g_0 . Along with this, the losses and noises introduce a feedback-like behavour into the system known as the dynamical optomechanical backaction². We shall revisit these coupled equations and their associated phenomena in later sections. But before getting into the intricacies, let us briefly discuss the qualitative aspects of the optomechancial interaction.

4 Basic Physics of Optomechanical Systems

4.1 Statics

Let us assume that the mechanical mirror is moved very, very slowly, akin to a static situation, i.e. for each position of the movable mirror, we give enough time to the mechanical oscillator to settle to the new state and in particular, for the light field intensity to adjust to the new length of the cavity. Now, the question is, what happens to the light field? As the mirror moves along, at some point it will be in resonance with the incoming laser light and the cavity will be filled up with light. So the radiation pressure force will also increase. We can plot the radiation pressure force (or equivalently the circulating light intensity) versus the displacement, as depicted in Fig. 3. One can see a typical Febry-Perot Lorentzian resonance line shape. The spacing between two such resonances is given by $\lambda/2$. The full width at the halfmaximum (FWHM) of the resonance is given by, λ $\frac{\lambda}{2F}$ where F is the so-called Finesse of the cavity. The corresponding potential versus displacement could also be plotted.

Fig. 3 —Top: Radiation pressure force (F_{RP}) and the intrinsic restoring force (*FHO*) versus displacement (*x*). Center*:* Radiation pressure potential (V_{RP}) and intrinsic harmonic potential (V_{HO}) versus x . Bottom: Total potential (V_t) versus x . The circles denote stable equilibrium positions.

It is clear that when there is no force, the potential vs. displacement curve has to be horizontal. When there is a force, the force pushes the mirror to the right, so we will have a dip and so on. This is a rather curious potential induced by the radiation pressure force. Please note that the full mechanical motion sees the standard restoring force potential plus this potential. One can see that at some places there is local minima. There are several such minima depending on the strength of the extra potential, provided by the light field intensity. The local minima of the overall potential as seen by the mechanical system correspond to stable equilibrium positions. The system can sit in any of these local minima depending on its history.

By changing some parameters, say the light intensity and looking at the output intensity, one can see that the system oscillates around a local minimum. However, it may also enter into a different local minimum and now if we reduce the light intensity it may stay in that minima rather than going back to the original minimum, giving rise to the phenomena of Hysteresis. This is happening owing to the existence of many equilibrium positions. Note that the original curvature of the potential (without the light field) gets changed owing to the presence of the light field. So

Fig. 4 — Radiation pressure force (F_{RP}) versus displacement (x) depicting cooling and heating for red-detuned and blue-detuned laser respectively. The green line denotes the effect of time-lag.

the spring constant of the mechanical oscillator now has an effective spring constant, as expressed in Equation (13). This is known as the optical spring effect.

$$
V_t = V_{HO} + V_{RP} = \frac{1}{2} K_{effx}^2
$$
 ... (13)

4.2 Dynamics

Let us now relax the static case. The mechanical oscillator or the cantilever now moves with a finite speed. The light field does not get time to completely track the mechanical motion. So we will have timelag effects. Let us imagine the following situation. If we move the mirror adiabatically, *i.e*. with zero speed, then we obtain the usual Lornetzian profile. Now, say we sweep along with a finite speed (refer to the solid green curve in Fig. 4). Then, as we reach the position x_a , the intensity has not built up yet to its full value, so we observe a smaller intensity, a smaller force. Again, as we reach position x_b , the intensity has not yet relaxed down to small value but retains memory of having been larger intensity before. So we will observe a displaced profile. So there will be a time lag between the motion and the observed intensity. The time scale of this time-lag is set by the cavity ring down rate, given by κ , which is also the photon decay rate.

In the dynamic case, the force is no longer a function of position at a given instant of time as was the case with static:

$$
F_{RP} \neq F_{RP}(x(t)) \tag{14}
$$

But $F_{RP}(t)$, the force at a given time depends on the full pre-history of the motion of x because that determines how the light field builds up and depletes again.

$$
F_{RP} = F_{RP}(x(t^{'}), t^{'} \le t) \tag{15}
$$

This force is no longer a conservative force. So we cannot write down a potential. It implies this force generates some friction. What are the consequences then?

To understand this, let us revert back to the resonance curve for the adiabatic case, denoted by the solid black curve in Fig. 4. It may be noted here that even in thermal equilibrium, the harmonic oscillator undergoes some oscillations whose amplitudes change with time. Let us follow through one such cycle of these oscillations, say at position x_a . As we approach the resonance, the force is little bit smaller than earlier due to time lag (as it still had to build up) and then as we go back, we have already reached the higher intensity and the force will remain high for some time than the adiabatic case. So the force in the two halves will not be identical in magnitude. So as a consequence, if we calculate the work done by the radiation pressure force in such a cycle, it will turn out to be non-zero. In fact,

$$
\oint F_{RP} dx < 0 \tag{16}
$$

This means, the force provided by the light field extracts energy from the mechanical motion, inducing extra damping in the mechanical oscillator. This is called light induced damping or optomechanical damping, *γom*. So, the total damping of the mechanical oscillator will be due to both the mechanical damping (*γ*) and the optomechanical damping (*γom*).

$$
\gamma t = \gamma + \gamma_{om} \tag{17}
$$

Now, whenever there is extra damping but no extra fluctuations, then this damping can simply be used to damp away the thermal fluctuations. Thermal fluctuations always arise as an equilibrium between damping that wants to extract energy and thermal random force that comes from outside that tries to heat up the system. In thermal equilibrium we have a balance between the two. So if we increase the damping we will be able to effectively reduce the thermal fluctuation.

$$
\oint F_{RP} dx < 0 \Rightarrow \text{extra damping}
$$
\n
$$
\Rightarrow \text{light} - \text{induced cooling} \qquad \qquad \dots (18)
$$

This is good news! Because the typical refrigerators in Lab are not good enough to cool mechanical systems down to the ground state. We can then exploit these extra mechanisms to cool the

oscillator further down. Note that, the situation we have considered above has a cavity length smaller compared to the resonance one. This implies that: *ωo>ω^l* , *i.e*. the laser is red-detuned. If we place the cantilever in the position, x_b (please refer to Fig. 4), we will have a situation where the cavity length is longer than the resonance one. It will correspond to the case, $\Delta_0 > 0$, *i.e.* the laser is blue detuned. In this configuration, the laser light will dump energy to the mechanical mirror, thereby heating it. Thus,

$$
\Delta_0 < 0: \text{Cooling}; \ \gamma_{om} > 0
$$
\n
$$
\Delta_0 > 0: \text{Heating}; \ \gamma_{om} < 0 \qquad \qquad \dots (19)
$$

5 Classical Regime of Cavity Optomechanics

To understand the quantum regime of cavity optomechanics in a better way, let us first explore a classical model of optomechanical systems. Such a description can be obtained from the QLEs in Equations (12) by analyzing the complex field amplitudes $\alpha = \langle a \rangle$ and $\beta = \langle b \rangle$. Utilizing the timeaverage properties of the noises, we obtain the coupled set of equations

$$
\dot{a} = -\left(\frac{k}{2} - i\Delta\right)\alpha + A_l, \n\dot{\beta} = -\left(\frac{\gamma}{2} - i_{\omega m}\right)\beta + ig_0 a^* a \qquad \qquad \dots (20)
$$

where $\Delta = \Delta_0 + g_0(\beta^* + \beta)$ is the effective detuning.

The classical equations of motion described in Equations (20) lead to some interesting observations. To analyze these, let us first assume that the optical and mechanical modes only deviate slightly from their steady-state values. This lets us linearize the dynamics around the steady state and study the effect of the classical deviations on the characteristics of the optical and mechanical modes.

5.1 Steady State and Bistability

In the long-time limit, the modes can be thought of as entering a steady-state such that their derivatives *d*⟨O⟩*/dt* are approximately equal to zero. We then obtain the steady-state mode amplitudes as

$$
\alpha_{s} = \left(\frac{A_{l}}{\frac{k}{2} - i\Delta}\right)
$$

$$
\beta_{s} = \left(\frac{ig_{0}|\alpha_{s}|^{2}}{\frac{y}{2} + i_{\omega m}}\right)
$$
...(21)

Equations (21) give rise to a cubic equation in the *mean optical occupancy* $N_o = |\alpha_s|^2$, marking two

categories of steady-state solutions. One solution has one real root while the other one has three real roots. The latter case is the multistable steady-state regime (shaded regions in Fig. 5 (a)). However, the middle branch of solutions is not traversed while varying the detuning and the system displays discontinuous jumps between the upper and lower states displaying a hysteretic behaviour¹³. As such, in the second regime, the system can be treated as effectively bistable⁷.

Exercise: Derive the cubic equation in *No* and verify the bistability curve in Fig. 5 (a).

One can also analyze the stability of the obtained steady-state values of α_s from the cubic in N_o by utilizing the Routh-Hurwitz criteria for nonlinear ordinary differential equations¹⁴. Such an examination is usually performed to locate the monostable branches of the system and drive the system away

Fig. 5 — (a) Number of intracavity photons (N_o) with variation in the laser detuning $(∆₀)$ for different values of optomechanical coupling (g_0) . The shaded areas denote the regions of bistability. (b) Stability of the system for different values of the laser detuning (Δ_0) and laser amplitude (A_l) calculated using the Routh-Hurwitz criteria. Here 'S' denotes a stable branch whereas 'U' denotes an unstable branch. The parameters used for the plots (in units of ω_m) are $A_l = 5.0$, $\gamma = 0.005$ and $\kappa = 0.15$.

from instability¹⁵. A typical plot for stable and unstable branches is shown in Fig. 5(b).

5.2 Response to an External Force

In order to study the linear response of the system to an external force F_{ext} acting on the mirror, we write the classical devations in the optical mode amplitude and the mechanical displacement as $\delta \alpha = \alpha - \alpha_s$ and $\delta q = q - q_s(q = \langle x \rangle)$ respectively. In the frequency domain, the corresponding coupled equations can be obtained as

$$
\begin{aligned}\n\left(-i\omega + \frac{k}{2} - i\Delta\right)\delta\alpha(\omega) &= iG\alpha_s q(\omega) \\
\left(-m\omega^2 + m\omega_m^2 - im\gamma\omega\right)q(\omega) \\
\left(-\hbar G(\alpha_s\delta\alpha * (-\omega) + \alpha_s^*\delta\alpha(\omega)) + F_{ext}(\omega)\right) \\
\dots (22)\n\end{aligned}
$$

where we have used the effective detuning ∆=∆0+*Gqs*(*qs* is the steady-state displacement) and the fact that $F[\delta \alpha^*(t)] = \delta \alpha^* (-\omega)$.

Exercise: Derive Equations (22). Hint: Use the relations $x = x_{\text{ZP}}(b^{\dagger} + b)$ and $p = ip_{\text{ZP}}(b^{\dagger} - b)$.

Now, the first equation can be written as $\delta \alpha(\omega) =$ $iG\alpha_s\chi_o(\omega)q$, where

$$
x_o(\omega) = \frac{1}{\frac{k}{2} - i(\Delta + \omega)} \qquad \qquad \dots (23)
$$

is the optical susceptibility, which relates the variation of the optical amplitude with variation in the mechanical motion. A similar expression for mechanical susceptibility can be obtained in the absence of optomechanical coupling as

$$
x_m(\omega) = \frac{1}{m(\omega_m^2 - \omega^2) - i m \gamma \omega} \qquad \qquad \dots (24)
$$

such that $q(\omega) = \chi_m(\omega) F_{ext}(\omega)$ relates the external force with the variation in mechanical displacement.

In the presence of optomechanical coupling, the mechanical susceptibility gets modified to

$$
x(\omega) = \frac{1}{\frac{1}{xm(\omega)} - \Sigma(\omega)}
$$
 ... (25)

where the optomechanical self energy is defined as

$$
\Sigma(\omega) = 2im\omega_m g_s^2(x_o(\omega) - x_o^*(-\omega)) \qquad \dots (26)
$$

with $g_s = Gx_{\text{ZP}}|\alpha_s| = g_0|\alpha_s|$. The introduction of $\Sigma(\omega)$ in the mechanical response leads to two characteristic phenomena in a cavity optomechanical system as discussed next.

5.3 Optomechanical Damping

From the second equation of Equation (22), it is evident that the imaginary part of $\Sigma(\omega \approx \omega_m)/(m\omega_m)$ gives the optomechanical damping rate,

$$
\gamma_{om} = g_s^2 k \left\{ \frac{1}{k_4^2 + (\omega_m + \Delta)^2} \middle| \frac{1}{k_4^2 + (\omega_m - \Delta)^2} \right\} \qquad \dots (27)
$$

The effective mechanical damping rate can then be expressed as a sum of the original mechanical damping rate *γ* and this new rate as discussed in Section 4.2. Thus, depending on the the value of *γom*, the mechanical motion can either encounter cooling or heating.

In Fig. 6, we plot *γom* as a function of the effective detuning ∆. It can be seen that when the cavity decay rate is much smaller than the mechanical frequency, *i.e.*, $\kappa \ll \omega_m$, the total damping increases around $\Delta = -\omega_m$. This cools down the mechanical oscillator. Whereas, around $\Delta = \omega_m$, the damping decreases and the mechanical oscillator heats up. The first situation also corresponds to the resonant absorption of a phonon to accomodate a blue-shifted photon inside the cavity, thereby cooling the mechanical oscillator. On the other hand, the second scenario may lead to the excitation of a phonon with a red-shifted photon inside the cavity. The regime where $\kappa \ll \omega_m$ is known as the resolved sideband regime. Here, the line width of the cavity mode is small enough to resolve the blue-shifted or red-shifted photons exiting the cavity. **Exercise:** What happens when *γom<* −*γ*?

5.4 Optical Spring Effect

It can also be seen that the real part of Σ(*ω* ≈ ω_m / $(2m\omega_m)$ is related to the frequency shift in the mechanical mode induced by the optical field,

Fig. 6 — Optomechanical damping (*γom*) as a function of the effective detuning $(∆)$.

It can be seen that the mechanical oscillator's response is either enhanced or slowed down by the optical field. This phenomena where the mechanical spring constant is altered by the optical field is known as the optical spring effect.

Figure 7 shows a typical plot of the frequency shift as a function of the effective detuning. When $\kappa \gg \omega_m$, the spring gets stiffer when $\Delta > 0$, *i.e.*, when the laser is blue-detuned. On the other hand, when ∆ *<*0, *i.e*., when the laser is red-detuned, the spring gets softer. However, if we work in the resolved sideband regime $\kappa \ll \omega_m$, the stiffening or softening of the spring can be appropriately adjusted by tuning the laser near $|\Delta| = \omega_m$.

Exercise: What happens when $\delta \omega_m < -\omega_m$ in the red-detuned regime?

6 Quantum Optomechanics

In Section 3.2, we mentioned that optomechanical cavities are typical open quantum systems. A cavity optomechanical system is easy to deal quantum mechanically as the Hamiltonian describing such systems are akin to the so-called Jaynes Cummings $model¹$. Below, we give a brief description of the linearized cavity quantum optomechanics.

6.1 Equations of Fluctuations

When the cavity is strongly driven, the radiation pressure force enhances considerably due to the large number of intracavity photons. In such a scenario, even for small values of optomechanical coupling, the system can be approximated by a linearized description. This means that the mode operators can be expressed as a sum of their classical mean amplitudes and the quantum fluctuations around tese classical values, that is, $a = \alpha + \delta a$ and $b = \beta + \delta b$. The coupled equations for the quantum fluctuations can therefore be obtained from Equations (12) as,

Fig. 7 — Mechanical frequency shift $(\delta \omega_m)$ as a function of the effective detuning $(∆)$.

$$
\delta \dot{\alpha} = -\left(\frac{k}{2} - i\Delta\right) \delta \alpha + i_g (\delta b^{\dagger} + \delta b)
$$

+ $\sqrt{k a_{in}}$,
 $\delta \dot{b} = -\left(\frac{\gamma}{2} - i_{wm}\right) \delta b + i (g \delta \alpha^{\dagger} + g * \delta \alpha)$
+ $\sqrt{\gamma b_{in}}$...(29)

Here, $\Delta = \Delta_0 + g_0(\beta^* + \beta)$ is the effective detuning defined earlier, and $g = g_0 \alpha$ is known the effective optomechanical coupling constant⁷. Thus, we see that the optomechanical coupling strength is enhanced by the optical mode amplitude. It may also be noted that since the amplitude of fluctations is much smaller than their classical values, we have ignored the second-order terms in *δa* and *δb* under the linearized approximation.

Exercise: Derive Equations (29).

One can also define the fluctuation quadratures for the optical mode $(\delta X = (\delta a^{\dagger} + \delta a)/2, \delta Y = i(\delta a^{\dagger} - \delta a)/2$ and the mechanical mode, $(\delta Q = (\delta b^{\dagger} + \delta b)/2, \delta P =$ $i(\delta b^{\dagger} - \delta b)/2$, and write a compact form of the dynamics as,

$$
\dot{u}(t) = A(t)u(t) + n(t) \tag{30}
$$

where $u = (\delta X, \delta Y, \delta Q, \delta P)^T$, *A* is known as the drift matrix, and n is the vector containing the noises induced in the quadratures.

Exercise: Obtain the expressions for the drift matrix *A* and the noise vector *n*.

6.2 Linearized Hamiltonian

 Γ

The Hamiltonian describing the dynamics of the fluctuations in Equations (29) can be written as⁷

$$
H_{lin} = -\hbar \Delta \delta \alpha^{\dagger} + \delta \alpha + \hbar_{\omega m} \delta b^{\dagger} + \delta b
$$

-
$$
\hbar (g \delta \alpha^{\dagger} + g^* \delta \alpha) + (\delta b^{\dagger} + \delta b) \qquad \dots (31)
$$

A pictorial depiction of this linearized interaction is shown in Fig. 8. The linearized Hamiltonian also explains a variety of interesting physical phenomena reported in optomechanical systems. Let us briefly analyze these. Assuming a simple scenario where the classical values settle down to a steady state and the phase of the laser light is adjusted in such a way that *α* is real, *i.e.*, $g = g_0 \alpha = g_0 |a_s| = g_s$, we obtain a simplified Hamiltonian

$$
H_{lin} = -\hbar \Delta \delta \alpha^{\dagger} + \delta \alpha + \hbar_{\omega m} \delta b^{\dagger} + \delta b
$$

-
$$
\hbar g_s (\delta \alpha^{\dagger} + \delta \alpha) + (\delta b^{\dagger} + \delta b) \qquad \dots (32)
$$

It can be clearly seen that this Hamiltonian features a position-position optomechanical interaction which is enhanced by the effective coupling constant. It is also evident from Equations (29) that the displacement of the mechanical oscillator is proportional to the phase shift of the cavity field. Therefore, measurement of the phase of the output field of the cavity provides information on the position of the moveable mirror and this facilitates the readout of the mechanical position. For details on readout and measurement, the readers may refer to 1,7,2,16 .

When the cavity is driven, the light scattered by the mechanical mirror gives rise to Stokes and anti Stokes sidebands where a quanta of mechanical energy is either absorbed or excited by the light field respectively. Depending on the detuning of the laser, this leads to either cooling or heating as discussed in the previous sections. These processes can be mathematically visualized by writing the Hamiltonian of Equation (32) in the interaction picture as

$$
H_{int} = -\hbar g_s \left[\{ \delta \alpha^{\dagger} \delta b e^{-i(\Delta + \omega m)} + \delta \alpha \delta b^{\dagger} e^{i(\Delta + \omega m)} \} + \{ \delta \alpha^{\dagger} \delta b^{\dagger} e^{-i(\Delta - \omega m)} + \delta \alpha \delta b e^{i(\Delta - \omega m)} \} \right] \dots (33)
$$

Exercise: Derive Equation (33).

Under the rotating wave approximation $(RWA)^7$, we obtain the following forms of interactions that lead to the two distinct phenomena of cooling and heating.

Fig. 8 — An illustration of the linearized optomechanical interaction. The cavity mode is assumed to be connected to a vacuum bath whereas the mechanical mode is in contant with a thermal environment⁸.

Beam-splitter Interaction and Cooling: In the red-detuned regime, when $\Delta = -\omega_m$, the interaction Hamiltonian under RWA takes the form of a beam splitter interaction

$$
H_{int} = -\hbar g_s \left(\delta \alpha^\dagger \delta b + \delta \alpha \delta b^\dagger \right) \tag{34}
$$

Since the mechanical mode is at a higher temperature than the optical mode, such a Hamiltonian preserves the phonon de-excitation process and this leads to a cooling effect in the mechanical motion. Cooling of the mechanical mode is a requirement for most quantum optomechanical applications and various schemes have been proposed to cool the mechanical oscillator to its quantum ground state 17,18 .

Squeezed Interaction and Heating: Similarly, when $\Delta = \omega_m$ in the blue-detuned regime, the Hamiltonian takes a squeezing interaction form

$$
H_{int} = -\hbar g_s (\delta \alpha^{\dagger} \delta b + \delta \alpha \delta b^{\dagger}) \qquad \qquad \dots (35)
$$

However, the resonant interaction of the modes suppresses the photon de-excitation process and this leads to heating or amplification of the mechanical mode through simultaneous excitation of an optical and mechanical quanta. Additionally, this form can also be used to squeeze the variance of the position fluctuations $(\langle Q^2 \rangle)$ of the mechanical mode at the exense of increased variance in the momentum fluctations $({\langle P^2 \rangle})$ ^{19,20}. This is routinely used in interferometric setups to enhance the sensitivity of the mechanical motion 21,22 .

6.3 Macroscopic Quantum Phenomena

Apart from phenomena like ground state cooling and mechanical squeezing which are used to prepare highly-sensitive mechanical oscillators, optomechanical systems also provide a suitable test bed for the study of quantum phenomena in the macroscopic domain. An important ingredient in the calculation of most of the figure of merits for these phenomena is the correlation matrix²³

$$
V_{ij} = \frac{1}{2} \langle u_i u_j + u_j u_i \rangle \quad ...(36)
$$

Using the formal solution for Equation (30) as $u(t) = M(t)u(0) + \int_0^t ds M(s)n(t-s)$ $\int_0^t ds M(s) n(t-s)$, where $M(t)$ $=\exp[At]$, it can be shown that the correlation matrix follows the dynamical equation of motion

$$
\dot{V}(t) = AV(t) + V(t)A^{T}(t) + D \qquad \dots (37)
$$

where the noise correlations are contained in $D = diag$ [*κ/*2*, κ/*2*, γ*(*nth* + 1*/*2)*, γ*(*nth* + 1*/*2)].

Exercise: Derive Equation (37). Detailed Soloutions of all the exercise can be found in Ref. 24 .

It is important to note here that the stability of the formal solution is necessary to obtain the dynamical form of the correlation matrix. This can be done by analyzing the eigenvalues of A through the Routh Hurwitz criteria introduced in Section 5.1. With this, let us briefly introduce three quantum phenomena that are being extensively studied in recent years. The inquisitive reader may refer to the cited articles for further insights on the mathematical formalism of each of these phenomena.

State-transfer: Since mechanical decays are much smaller than that of their optical counterparts, encoding the optical state in the mechanical mode can be done to store information for longer durations. Also, a common mechanical mode can be used to transduce information between optical and microwave signals 25 . Schemes to transfer the optical state from one node of a many-body optomechanical system to another has applications in the design of quantum networks²⁶. Transduction between optical, mechanical and microwave domains is currently an active field of research²⁷⁻²⁹.

Entanglement: Entanglement is a extremely important resource for quantum information processing and quantum communication $30,31$. The quantification of entanglement between the optical and mechanical elements of an optomechanical system was pioneered by Vitali *et al.* in 2008²³. Since then, numerous schemes have been proposed to strongly entangle optical and mechanical components of single as well as many-body optomechanical systems $8,32,33$. Entangling microwave and optical signals to create hybrid electro-optomechanical converters can find applications in the development of quantum sensors and radars in the radio-frequency \tilde{d} omain^{10,34,37}.

Synchronization: In the classical world, synchronization — a tendency of oscillators to sympathetically adjust their rhythms — is a ubiquitous phenomena observed across different $domains^{38}$. . Several measures of quantum synchronization have also been proposed in recent years as this phenomena is gathering a good amount of interest in the deep quantum regime³⁵⁻⁴³. Since an optomechanical system can undergo self-oscillations, coupled optomechanical systems can also display synchronization $42,44,45$. Long-distance quantum

synchronization can find applications in quantum communication and quantum networks 46-49 .

7 Conclusion and Future Prospects

In this tutorial, we introduced an optomechanical system with an optomechanical coupling of the first order. We then systematically derived the classical and quantum dynamics for such a system, detailing on some characteristic properties and phenomena. We believe that the theories discussed will help the reader to get started in the field of optomechanics and analyze a variety of phenomena for linearizable quantum optomechanical systems.

In the last two decades, studies have also explored the effect of higher-order coupling terms and noises⁵⁰⁻⁵⁵, photon blockade^{56,57}, induced noises⁵⁰⁻⁵⁵, photon blockade^{56,57}, induced transparency⁵⁸⁻⁶⁰ and collective nonlinear dynamics 61,62 . It is also inspiring to see emerging interdisciplinary studies that utilize the formalism of optomechanics δ , 63-65. We believe that the field of optomechanics shall serve as a versatile platform to propose, interpret or predict quantum phenomena as well as advance quantum technologies in the years to come.

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